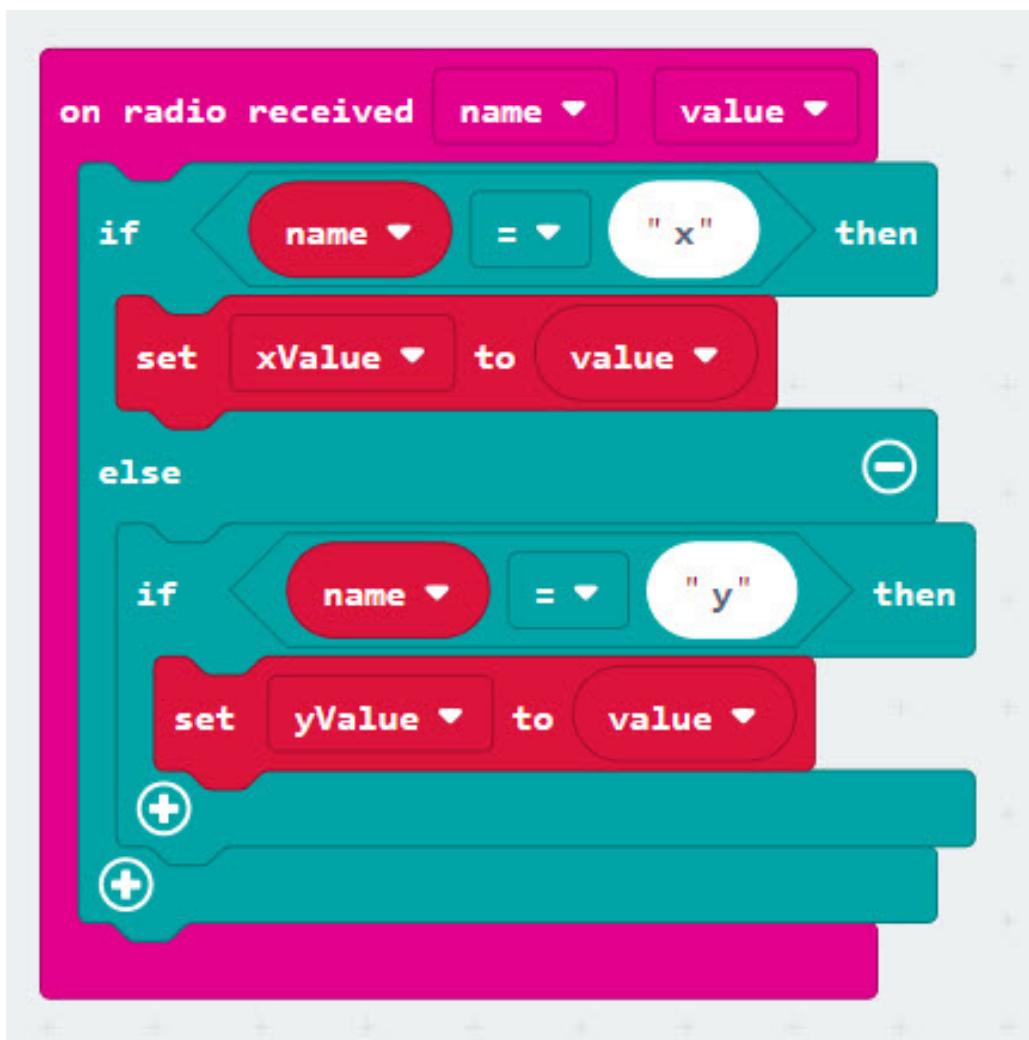
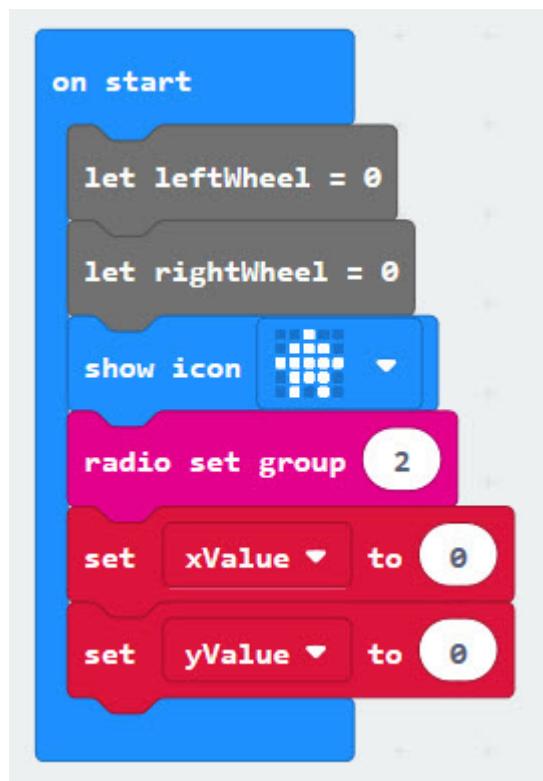


# Alfa - 3 modtag



```
forever
  set [leftwheel v] to [yValue v + v xValue v]
  set [rightwheel v] to [yValue v - v xValue v]
  if [leftwheel v > v 0] then
    kitronik.motorOn(kitronik.Motors.Motor1, kitronik.MotorDirection.Forward, leftwheel)
  else
    kitronik.motorOn(kitronik.Motors.Motor1, kitronik.MotorDirection.Reverse, Math.abs(leftwheel))
  +
  if [rightwheel v > v 0] then
    kitronik.motorOn(kitronik.Motors.Motor2, kitronik.MotorDirection.Forward, rightwheel)
  else
    kitronik.motorOn(kitronik.Motors.Motor2, kitronik.MotorDirection.Reverse, Math.abs(rightwheel))
```